

SMIL survival kit

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1 Introduction

This document contains a short list of functions with a quick description. The complete documentation can be found at <http://smil.cmm.mines-paristech.fr/doc/modules.html>.

Note: optional parameters are between square brackets [*optional*].

2 import SMIL library

In order to import SMIL library type the following command:

```
from smilPython import *  
or  
import smilPython as sm
```

If the second version is used, the suffix **sm** will be necessary when calling SMIL functions.

In order to run an existing script type:

```
execfile("myscript.py")
```

3 I/O images

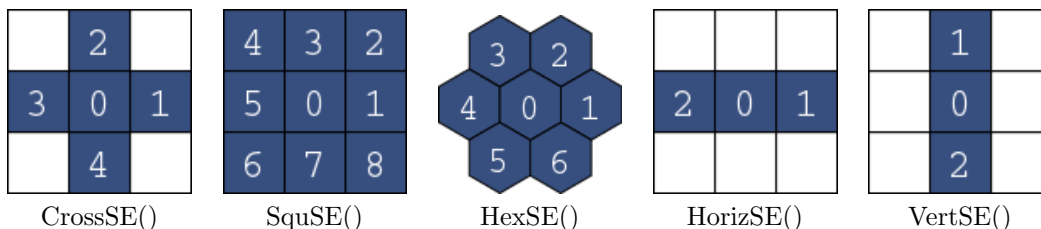
- To read an image:
`im = Image("images/toto.png")`
- To write an image:
`write(im,"filename.png")`
- To create a new image based on the dimensions of a given image (but not to copy the contents):
`im2 = Image(im)`
- To create a new image based on the dimensions of a given image but with a different depth:
`im2 = Image(im,"UINT16")`
- To display an image:
`im.show()`
- To display an image in false colors:
`im.showLabel()`

4 Pixel-based functions

- To copy an image into another one:
copy(im,im2)
- To set the image to zero:
im << 0
- To invert the image
inv(imin,imout)
- To add a constant (or an image):
add(imin,constant_or_image,imout)
- To subtract a constant (or an image):
sub(imin,constant_or_image,imout)
- Returns the maximum value of im:
maxVal(im)
- Returns the minimum value of im:
minVal(im)
- To compare an image to a constant or another image:
compare(imin,condition,a,b,c, imout)
a, b and c can be images or scalars. imin is compared to a according to the given condition. If result is true, parameter b is set in imout. Otherwise the corresponding imout pixel is set to c.
For example
compare(im1,">", im2, im1,im2,imomut)
is equivalent to **sup**(im1,im2,imout)
- To compute the sup of two images:
sup(im1,im2,imout)
- To compute the inf of two images:
inf(im1,im2,imout)
- Threshold:
threshold(im,minval,maxval,trueval,falseval,imout)
- Otsu threshold :
threshold(im,imout)
- Scale : if im has the size (W,H), the size of imout will be (W*factor_x, H*factor_y). imout should be allocated first (imout = Image()).
scale(im,factor_x, factor_y,imout)

5 Structuring elements

5.1 Already defined structuring elements :



5.2 Default structuring element

If not specified, default SE is used in most morphological functions. As an optional parameter, SE is usually the last one.

```
erode(imin,imout)
erode(imin,imout, CrossSE())
erode(imin,imout,CrossSE(size))
```

5.3 Modify default SE

Get Default SE: `print Morpho.getDefaultSE()`. If not modified, `HexSE()` is used by default.

Set default SE : `Morpho.setDefaultSE(CrossSE())`. `CrossSE()` becomes default SE.

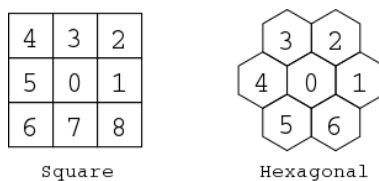
5.4 Define other SEs

Construct a structuring element with points defined by their indexes:

StrElt(HexFlag, PointList) :

For example:

`mySE1= StrElt(False,(0,1,5))` is equivalent to `HorizSE()`.



6 Morphological Erosion, Dilation, Opening, Closing

If not specified, default SE is used in most morphological functions. As an optional parameter, SE is usually the last one.

- Erosion with default SE:
`erode(im,imout)`

- Erosion with other SE:
`erode(im,imout,CrossSE())`
- Erosion with an homothetic SE:
`erode(im,imout[, CrossSE(size)])`
- Dilation (idem for optional SE).
`dilate(im,imout[,CrossSE(size)])`
- Morphological opening (idem for optional SE).
`open(im,imout[,CrossSE(size)])`
- Morphological closing (idem for optional SE).
`close(im,imout[,CrossSE(size)])`

7 Reconstruction

- Reconstruction by dilation
`build(imMark,imRef,imOut[,nl])`
- Reconstruction by erosion
`dualBuild(imMark,imRef,imOut[,nl])`
- hBuild: reconstruct by dilation from f-h:
`hBuild(im,h,immout[,nl])`
- hDualBuild: reconstruct by erosion from f+h:
`hDualBuild(im,h,immout[,nl])`
- hMaxima: regional maxima after hBuild (reconstruction from f-h),
`hMaxima(im,h,immax[,nl])`
- hMinima: regional minima after hDualBuild (reconstruction from f+h),
`hMinima(im,h,immin[,nl])`
- hMaxima: regional maxima after razing function f constrained by f-h,
`hMaxima(im,h,immax[,nl])`
- hMinima: regional minima after flooding function f constrained by f+h,
`hMinima(im,h,immin[,nl])`

8 Filtering

Opening and closing are also morphological filter. Other filters are given in this section:

- Alternate filter: an opening of size *size* followed by a closing of the same size.
AF(im,size,imout[,nl])
- Alternate sequential filter: $\phi_{size}\gamma_{size}\dots\phi_2\gamma_2\phi_1\gamma_1(im)$
ASF(im,size,imout[,nl])
- Opening by reconstruction: erosion of size *size* followed by reconstruction (by dilation):
buildOpen(imIn, imOut, se(size))
- Closing by reconstruction: dilation of size *size* followed by reconstruction (by erosion):
buildClose(imIn, imOut, se(size))
- Alternate filter combining buildOpen and buildClose of a give size:
buildAF(imIn, imOut, se(size))
- Alternate sequential filter combining buildOpen and buildClose of increasing sizes (up to size *size*):
buildASF(imIn, imOut, se(size))
- AreaOpen:
areaOpen(imIn, size, imOut)
- Alternate levelings:
ASF_Leveling(imIn, size, imOut,nl)

9 Connexity oriented functions

- Regional minima of imin :
minima(imin,imout[, nl])
- Regional maxima of imin:
maxima(imin,imout[, nl])
- **label**(im,imlabel[, nl]). Assign a different *label* (identifier) to each connected component.

10 Segmentation

- To compute the gradient:
`gradient(im,imout[,nl])`
- Watershed of *imgra* into *imws*:
`watershed(imgra,imws[,nl])`
- Watershed of *imgra* from markers *immark* into *imws*. Note: each marker should be identified with a different *label*.
`watershed(imgra,immark,imws[,nl])`
- Watershed of *imgra* from markers *immark*. Two output parameters *imws* with the watershed line and *imbasins* the labelled mosaic without the watershed line:
`watershed(imgra,immark,imws,imbasins[,nl])`
- Basins (labelled mosaic without watershed line) of *imgra*:
`basins(imgra,imbasins[,nl])`
- Basins (labelled mosaic without watershed line) of *imgra* from markers *immark*:
`basins(imgra,immark,imbasins[,nl])`
- Hierarchical segmentation based on extinction values: *imgra* is flooded and the computed extinction value is assigned to the minima in *imEV* image. *extinction_type* can be "d", "a" or "v" for dynamics, area or volume respectively.
`watershedExtinction(imgra,imEV, extinction_type [,nl])`
- A waterfall iteration of *imgra0* from *imws0*:
`waterfall(imgra0,imws0,imgra1,imws1[,nl])`
- Iteration of waterfall, *level* times:
`waterfall(imgra,level,imwf[,nl])`
- Extinction values based hierarchical segmentation:
`imFineSeg,MST = watershedEV(imgra,EVType[,nl])`
- Get a partition *imSeg* with *Nregions* from the hierarchy stored in MST graph:
`getEVLevel(imFineSeg, MST, Nregions, imSeg)`

11 Color

- Extract channels from a color image:
`im1,im2,im3 = extractChannels(colorim)`

- Combine channels into a color image:
colorout = combineChannels(im1,im2,im3)
- Get luminance:
im8 = Image(colorim,"UINT8")
RGBToLuminance(colorim,im8)
- Color conversions:
colorim2 = Image(colorim)
 - RTBToXYZ(colorim,colorim2)
 - RGBToLAB(colorim,colorim2)
 - RGBToHLS(colorim,colorim2)
- Color gradients:
 - imgraLAB= gradient_LAB(colorim,nl)
 - imgraHLS= gradient_HLS(colorim,nl)